Much of the Firmware tuning can only be completed after initial tests are done with the built drone. This list of parameters are the first that we determined will need to be modified after the initial tests are finished.

Q\_ENABLE

Q\_M\_PWM\_MIN

Q\_M\_PWM\_MAX

Q\_A\_RAT\_RLL\_P

Q\_A\_RAT\_PIT\_P

Q\_M\_SPIN\_ARM